

TODAY Wed Jan 30, 2019

(17)

Quiz $F = cv$ vs cv^2

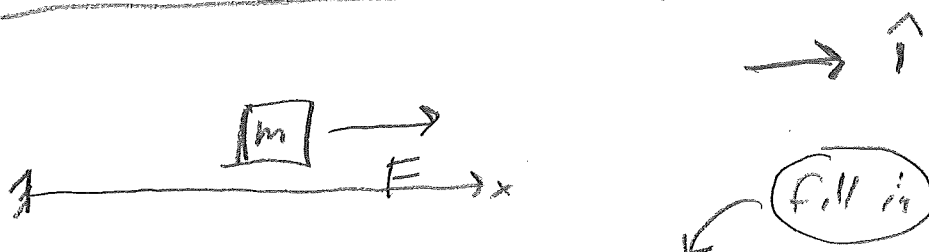
3 Thms in 1D dynamics
1) gen. examples of 1D dyn.

~~Num. methods cont'd~~

2) Examples

1) Quiz (see next ex)

Gen Ex 1D motion



I. Force laws : $F = \dots$

II. Kin : $\dot{x} = v$, $\dot{v} = a$

III. Laws of Mechⁿ $F = ma$

ex) $F = 0 \Rightarrow \boxed{\dot{v} = 0}$ or $a = 0$

"An object in motion . . ."

Quiz 1

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$\rightarrow V_0$ (same for both)



$m = m$

$$F_{D1} = cV \quad (1)$$



$$F_{D2} = cV^2 \quad (2)$$

V_0 is big

which one goes farther?
in the end.

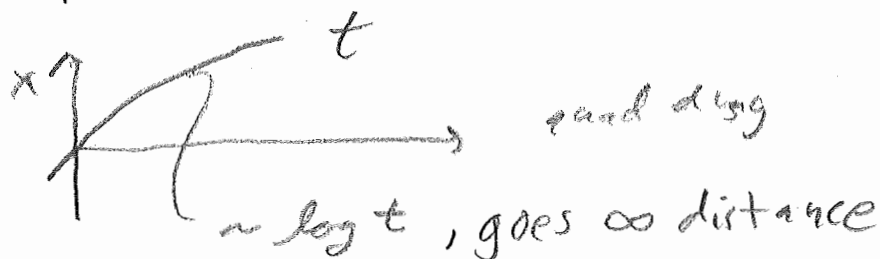
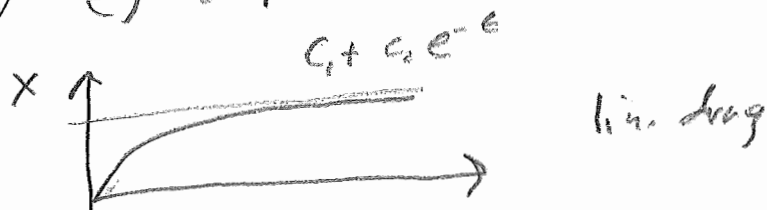
a) ①

b) ②

c) depends on c

d) depends on V_0

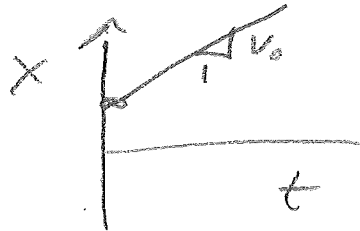
✓ e) depends on comb. of c, V_0 & m



$$\Rightarrow \dot{V} = 0 \Rightarrow V = V_0$$

$$\dot{x} = V \Rightarrow \boxed{x = x_0 + V_0 t}$$

$$\ddot{x} = 0 \Rightarrow$$



ex) $F = F_0 \Rightarrow \dot{V} = F_0/m \equiv a_0$

$$\Rightarrow V = V_0 + a_0 t$$

$$x = \frac{1}{2} a_0 t^2 + V_0 t + x_0$$

" $d = \frac{1}{2} a t^2$ " ANDY 5th
grade
report

~~$E = mc^2$~~ - Hawley Rising

etc

ex) $F = f(t)$

$$a(t) = \frac{f(t)}{m}$$

$$\dot{V} = a(t) = f(t)/m$$

$$V = \int f(t) dt / m + C_1$$

Math 1910

$$x = \int V dt / m + C_2$$

19

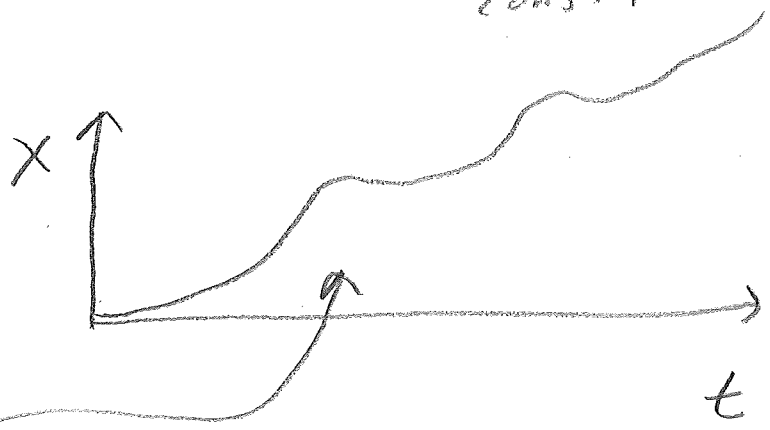
subex)

$$X_0 = 0$$

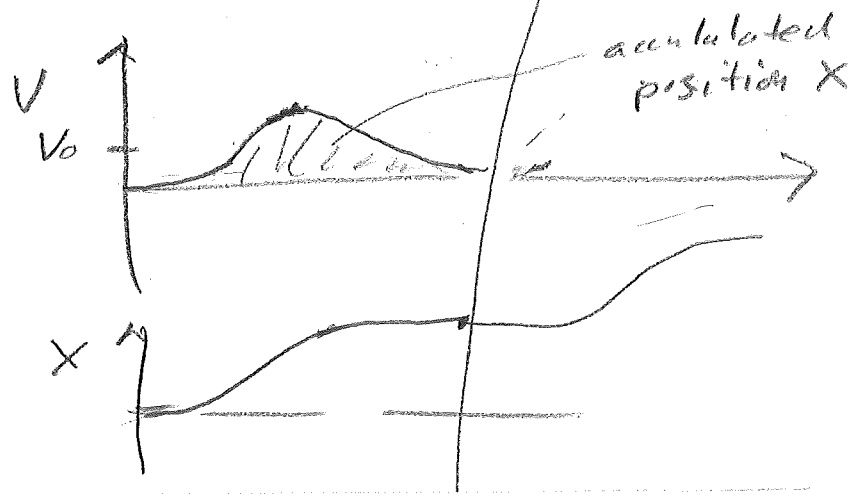
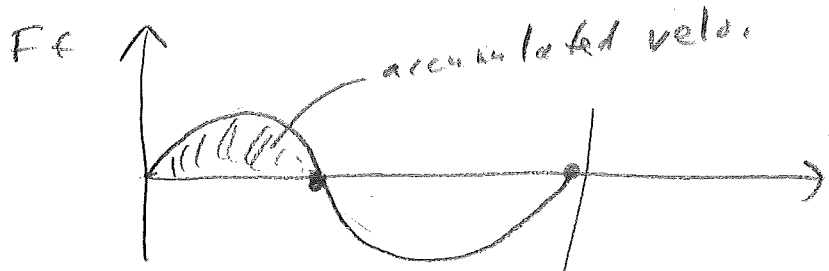
$$V_0 = 0$$

$$f(t) = f_0 \sin \omega t$$

↑ ↑
const.



- a) sine wave X
- b) " + const X
- c) " " const + lin fn. ✓



sqb ex) a.b. fcs of t

subsubex) $f(t) = \frac{C e^{-bt}}{t}$

$$\dot{V} = \frac{1}{m} \frac{C e^{-bt}}{t}$$

$\Rightarrow$ no analytic soln.
(even if $t_0 > 0$)

ex) $F = g(v)$

$$\Rightarrow a = \frac{1}{m} g(v)$$

$$\boxed{\dot{V} = \frac{1}{m} g(v)} \Rightarrow \text{separable eqn.}$$

$\hat{x} = v$ $\Rightarrow$ might have anal. soln.

subex) $F = -cV$

$$V = V_0 e^{-ct}$$

$$x = \dots \quad (\text{Quite problem})$$

subex) (last lecture) Quite problem

$$F = -cV|V|$$

$$V^2 \text{ if } V > 0 \\ V > 0$$

$$\Rightarrow \boxed{V = V_0 e^{-cx}}$$

$$\Rightarrow x \sim \log(t)$$

ex) $F = h(x)$ force is fn. of position (2)

$$\left. \begin{aligned} \dot{V} &= \frac{1}{m} h(x) \\ \dot{X} &= V \end{aligned} \right] \left[\begin{array}{l} \text{Cons of energy} \\ \Rightarrow V(x) \\ \uparrow \text{(not shown yet)} \end{array} \right]$$

subex)

$$h(x) = -kx$$

restoring
~~spring~~
Spring (linear)

$$\Rightarrow \boxed{m \ddot{X} + kX = 0}$$

or

$$\left[\begin{array}{l} \dot{X} = V \\ \dot{V} = -\frac{k}{m} X \end{array} \right] \Leftrightarrow \dot{Z} = f(Z)$$

rules of change $\leftarrow \rightarrow$ state

$$X = A \cos(\omega t) + B \sin \omega t$$

$$\omega = \sqrt{k/m}$$

ex) mix & match

subex) Most famous

$$\omega_f \neq \omega_n = \omega$$

$$\neq \sqrt{k/m}$$

$$\boxed{F = -kx - cV + F_0 \sin \omega_f t}$$

$\Rightarrow$

$$\dot{x} = v$$

$$\dot{v} = \frac{1}{m} (-kx - cv + F_0 \sin \omega t)$$

$$m\ddot{x} + c\dot{x} + kx = F_0 \sin(\omega t)$$

$x(t) = ?$

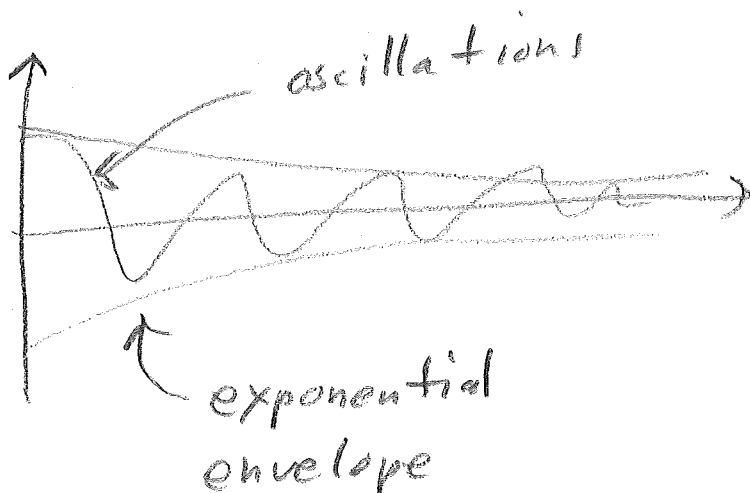
"Forced, damped harmonic oscillator"

subex)

c is small

$$F_0 = 0$$

underdamped vib. decay



Gen case of 1D motion

(23)

$$F = F(x, v, t)$$

$$\begin{cases} \dot{x} = v \\ \dot{v} = \frac{1}{m} F(x, v, t) \end{cases}$$

gov. eqn.

"EOM"

"Equations of motion"

Can solve (at least numerically)

$$\Rightarrow \underbrace{x(t), v(t)}_{\text{solution of EOM}}$$

Can know some things ahead of time: thms facts.

checks ✓ ✓ ✓

Thms

{ } . v

$$\{ F = ma \}$$

$$v F = m a \cdot v \\ \hookrightarrow \frac{dv}{dt}$$

$$v F = m \frac{d}{dt} \left(\frac{1}{2} v^2 \right)$$

$$\underline{FV} = \frac{d}{dt} \left(\frac{1}{2} m v^2 \right)$$

Power = $\dot{P}$

$$\underline{K_{in}, E_{in}} = \text{"~~E~~"}$$

$$\textcircled{E_K}, \text{~~T~~, ~~K~~}$$

$$\boxed{P = \dot{E}_K} \textcircled{1} \text{ power balance}$$

Next

$$\int \textcircled{1} dt$$

$$\int P dt = \int \dot{E}_K dt$$

$$\boxed{\int P dt = \Delta E_K} \textcircled{2}$$

"Power x time = Energy"

$$\int P dt = \int P \frac{dt}{dx} dx$$

$$= \int F v \frac{1}{v} dx$$

$$= \underbrace{\int F dx}_{\text{work}}$$

$$\boxed{\int \frac{F_{ax}}{w} = \Delta E_K}$$

Work = change in Kin. En.

$$\boxed{W = \Delta E_K}$$

Work = change in
Kin. Energy

Lin. Mon

$$\{ F = ma \}$$

$$\int \int dt$$

$$\int F dt = \int m a dt$$

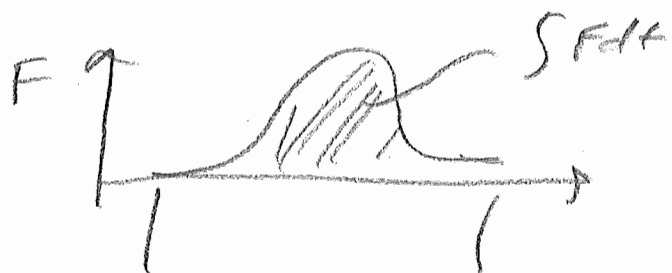
$$L \frac{dv}{dt}$$

$$\int F dt = m \Delta v$$

"Impulse"

$$mv = L = \text{lin. mon.}$$

not, nec. southly sudden



SUMMARY

$$* P = \dot{E}_K$$

$$* W = \Delta E_K, \quad \int P dt = \Delta E_K$$

$$* \int F dt = \Delta(mv) = \Delta L$$