

The kinetic energy of the system E_K is the sum over the kinetic energy of each particle,

$$E_K = \frac{1}{2} \sum_i m_i v_{i/O}^2,$$

where $v_{i/O}^2 = \mathbf{v}_{i/O} \cdot \mathbf{v}_{i/O}$ and the point O is origin of some Newtonian reference frame. The position of the center of mass $\mathbf{r}_{G/O}$ can be written as the mass-weighted average of the position of each particle $\mathbf{r}_{i/O}$,

$$\mathbf{r}_{G/O} = \frac{\sum_i m_i \mathbf{r}_{i/O}}{\sum_i m_i},$$

and similarly, the velocity of the center of mass $\mathbf{v}_{G/O}$ can be written as the mass-weighted average of the velocity of each particle $\mathbf{v}_{i/O}$

$$\mathbf{v}_{G/O} = \frac{\sum_i m_i \mathbf{v}_{i/O}}{\sum_i m_i}.$$

We may write the velocity of each particle in terms of the velocity of the center of mass and the velocity of the particle relative to the center of mass $\mathbf{v}_{i/G}$,

$$\mathbf{v}_{i/O} - \mathbf{v}_{G/O} = \mathbf{v}_{i/G},$$

which then, after expanding

$$v_{i/O}^2 = \mathbf{v}_{i/O} \cdot \mathbf{v}_{i/O} = v_{G/O}^2 + v_{i/G}^2 + 2\mathbf{v}_{G/O} \cdot \mathbf{v}_{i/G},$$

we retrieve the kinetic energy as

$$E_K = \frac{1}{2} \sum_i m_i v_{G/O}^2 + \frac{1}{2} \sum_i m_i v_{i/G}^2 + \mathbf{v}_{G/O} \cdot \sum_i m_i \mathbf{v}_{i/G}.$$

We denote $m_{\text{tot}} = \sum_i m_i$ as the total mass, so the first term is the kinetic energy of the center of mass

$$E_{KG} = \frac{1}{2} \sum_i m_i v_{G/O}^2 = \frac{1}{2} m_{\text{tot}} v_{G/O}^2.$$

The third term, using the previous relations, is seen to sum to zero by

$$\sum_i m_i \mathbf{v}_{i/G} = \sum_i m_i (\mathbf{v}_{i/O} - \mathbf{v}_{G/O}) = m_{\text{tot}} \mathbf{v}_{G/O} - m_{\text{tot}} \mathbf{v}_{G/O} = 0,$$

so we retrieve $E_K = E_{KG} + E_{K/G}$, where

$$E_{K/G} = \frac{1}{2} \sum_i m_i v_{i/G}^2.$$

Now, if we assume that all of the particles are part of a single rigid object, and since this problem is in two-dimensions, the velocity of each particle relative to the center of mass will be strictly due to planar rotation of the rigid object, i.e.

$$v_{i/G} = \omega_G r_{i/G},$$

where ω_G is the angular frequency at which the rigid object rotates. Upon seeing the appearance of the moment of inertia of the rigid object about its center of mass,

$$I_G = \sum_i m_i r_{i/G}^2,$$

we now have the simple relation

$$E_{K/G} = \frac{1}{2} I_G \omega_G^2.$$