

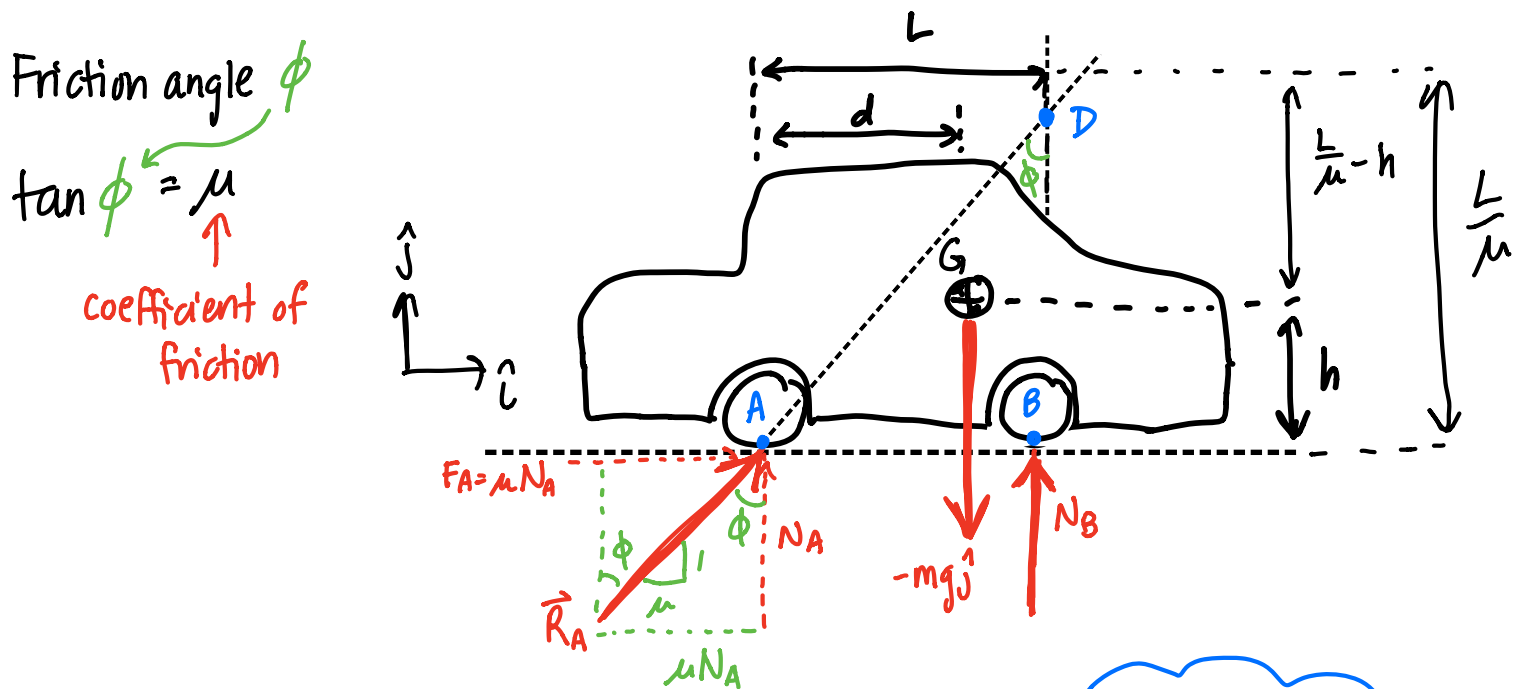
Today: ① Cars (Recap)

Max acceleration of rear wheel drive car?

Assume: μ, d, h, L, m, g

Assume: screeching (skidding) when we get max accel

Assume: car only translates $[\vec{a}_G = a_G \hat{i}]$



$$\text{AMB/D: } \sum \vec{M}_{/D} = \vec{H}_{/D}$$

$$\vec{r}_{G/D} \times -mg\hat{j} = \vec{r}_{G/D} \times m\vec{a}_G$$

→ algebra is skipped

$$\vec{r}_{G/D} = -\left(\frac{L}{\mu} - h\right)\hat{j} - (L - d)\hat{i}$$

$$\Rightarrow \left\{ (L-d) \cancel{mg} \hat{k} = \left(\frac{L}{\mu} - h \right) a_G \cancel{m} \hat{k} \right\}$$

$$\{ \} \cdot \hat{k} \Rightarrow a_G = \frac{(L-d)g}{\frac{L}{\mu} - h}$$

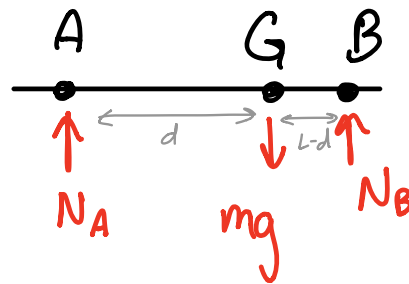
$$a_G = \left(\frac{1 - d/L}{1 - \mu h/L} \right) \mu g$$

check for special cases:

ex) $\mu = 0 \Rightarrow a_G = 0$ ✓

ex) $h = 0 \Rightarrow$

↓
no change of
 N_A and N_B
relative to statics
 $(L-d)N_B = dN_A$
 $N_A + N_B = mg$



$$N_A = \left(1 - \frac{d}{L} \right) mg$$

→ statics reasoning: $a_G = \frac{\mu N_A}{m}$
 $= \left(1 - \frac{d}{L} \right) \mu g$

→ dynamics: $\left(1 - \frac{d}{L} \right) \mu g = a_G$
 $h=0$

Calculate N_A & N_B :

LMB: $\sum \vec{F} = m\vec{a}$

$$\{(N_A + N_B - mg)\hat{j} + \mu N_A \hat{i} = ma_G \hat{i}\}$$

$$\{ \} \cdot \hat{i} \Rightarrow \mu N_A = ma_G = \frac{(1 - \frac{d}{L})}{(1 - \frac{\mu h}{L})} \mu mg$$

$$N_A = \frac{1 - \frac{d}{L}}{1 - \frac{\mu h}{L}} mg$$

$$\{ \} \cdot \hat{j} \Rightarrow N_A + N_B - mg = 0$$

$$N_B = mg - N_A$$

$$N_B = mg - \frac{1 - \frac{d}{L}}{1 - \frac{\mu h}{L}} mg$$

$$= mg \left(\frac{1 - \frac{\mu h}{L} - (1 - \frac{d}{L})}{1 - \frac{\mu h}{L}} \right)$$

$$N_B = \frac{\frac{d}{L} - \frac{\mu h}{L}}{1 - \frac{\mu h}{L}}$$

To make sense :

$$N_B \geq 0$$

$$\Rightarrow \mu > L/h \text{ (bottom)}$$

$$\text{or } \Rightarrow \mu > d/h \text{ (top)}$$

$d < L \Rightarrow$ problem is first w/ top of fraction

Not tipping $\Leftrightarrow$

$$\mu \leq d/h$$

$\hookrightarrow$ implies that G is below the line from A to D

What does this physically mean?

