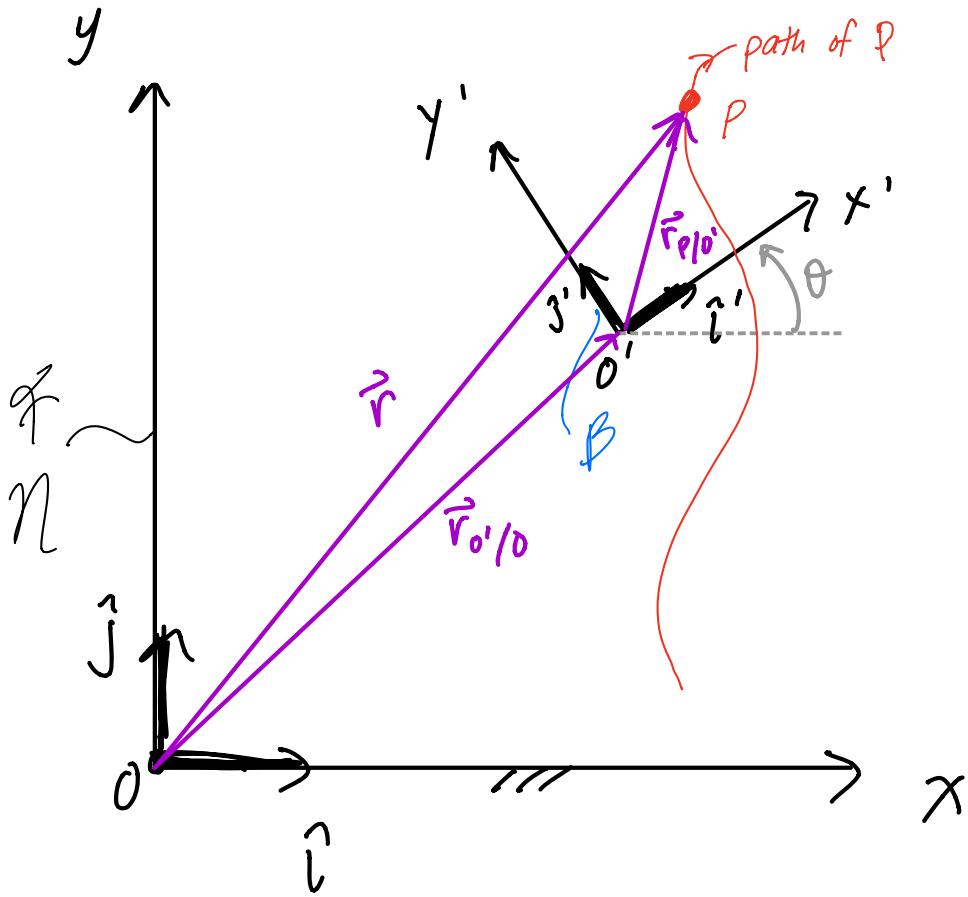


Today: Relative motion continued

Goal: use information from moving observers to find

$$\vec{v}_P = \vec{v}_{P/Q} \quad \& \quad \vec{a}_P = \vec{a}_{P/Q}$$



for dynamics, we want

$$\vec{r} = \vec{r}_{P/0}$$

$$\vec{v} = \vec{v}_{P/Q} = \dot{x}\hat{i} + \dot{y}\hat{j}$$

$$\vec{a} = \vec{a}_{P/Q} = \ddot{x}\hat{i} + \ddot{y}\hat{j}$$

We are given:

$$\vec{r}_{0'/0}, \vec{v}_{0'/0}, \vec{a}_{0'/0}$$

$$\vec{r}_{P/0'} = x'_{P/0'} \hat{i}' + y'_{P/0'} \hat{j}'$$

$$x_{P/0'} \hat{i} + y_{P/0'} \hat{j}$$

$$\vec{v}_{P/B} = \dot{x}'\hat{i}' + \dot{y}'\hat{j}'$$

$$\vec{a}_{P/B} = \ddot{x}'\hat{i}' + \ddot{y}'\hat{j}'$$

definitions of velocity & acceleration relative to a moving frame

use givens to find  $\vec{v}_{P/f}$  &  $\vec{a}_{P/f}$

$$\begin{aligned}\vec{r} = \vec{r}_P &= \vec{r}_{0'/0} + \vec{r}_{P/0'} \\ &= (x_{0'/0}\hat{i} + y_{0'/0}\hat{j}) + (x'_{P/0}\hat{i}' + y'_{P/0}\hat{j}')\end{aligned}$$

Recall:  $\dot{\hat{i}'} = \vec{\omega} \times \hat{i}$

$$\dot{\hat{j}'} = \vec{\omega} \times \hat{j}$$

$$\vec{v}_{P/f} = \vec{v}_P = \frac{d}{dt}(\vec{r}_P) = \frac{d}{dt}(\vec{r}_{0'/0}) + \frac{d}{dt}(\vec{r}_{P/0'})$$

$$\vec{v}_{P/f} = \vec{v}_{0'/f} + (\dot{x}'\hat{i}' + \dot{y}'\hat{j}') + (x'\dot{\hat{i}'} + y'\dot{\hat{j}'})$$

$\vec{v}_{P/B}$       +       $\vec{\omega} \times \vec{r}_{P/0'}$

$$\boxed{\vec{v}_{P/f} = \vec{v}_{0'/f} + \vec{v}_{P/B} + \vec{\omega} \times \vec{r}_{P/0'}}$$

\*  $\vec{v}_{P/0'} = \vec{v}_P - \vec{v}_{0'}$   $\neq \vec{v}_{P/B}$

\* listen to lecture to understand breakdown of all 3 terms

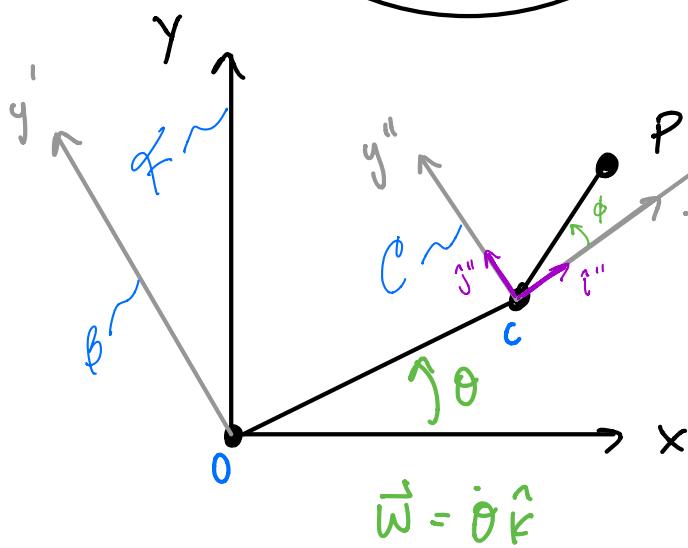
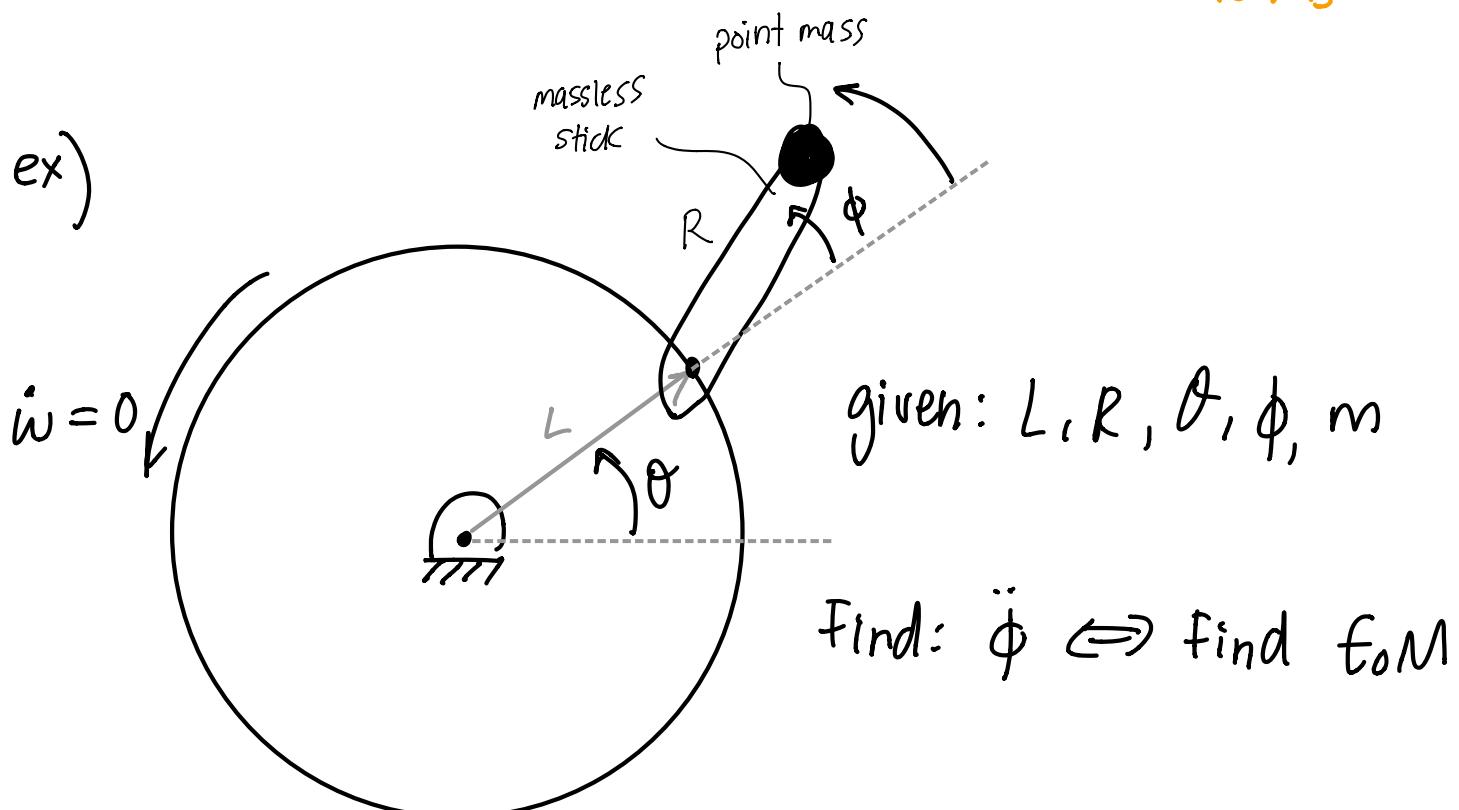
$$\vec{a}_{P/q} = \frac{d}{dt} (\vec{v}_{P/q})$$

\* read textbook for full derivation

$$\vec{a}_{P/q} = \vec{a}_{0'/0} + \vec{a}_{P/\theta} + -\omega^2 \vec{r}_{P/0'} + \dot{\vec{\omega}} \times \vec{r}_{P/0'} + 2\vec{\omega} \times \vec{v}_{P/\theta}$$

"The five term acceleration formula" \* listen to lecture to understand breakdown of all 5 terms

ex)



$$\vec{a}_P = \vec{a}_C + \vec{a}_{P/\theta} + -\omega^2 \vec{r}_{P/C}$$

$$+ \dot{\vec{\omega}} \times \vec{r}_{P/C} + 2\vec{\omega} \times \vec{v}_{P/C}$$

$$\vec{a}_{c/\cancel{f}} = -\omega^2 \vec{r}_{c/0} = -\omega^2 \cdot \hat{i} "L"$$

$$\vec{a}_{p/c} = \ddot{\phi} \hat{k} \times \vec{r}_{p/c} + -\dot{\phi}^2 \vec{r}_{p/c}$$

$$-\omega^2 \vec{r}_{p/c} = -\omega^2 \vec{r}_{p/c}$$

$$\vec{\omega} \times \vec{r}_{p/c} = \vec{\omega} \times \vec{r}_{p/c}$$

$$2\vec{\omega} \times \vec{v}_{p/c} = 2\vec{\omega} \times (\dot{\phi} \hat{k} \times \vec{r}_{p/c})$$

put it all  
together  
to get  $\ddot{\phi} = \dots$