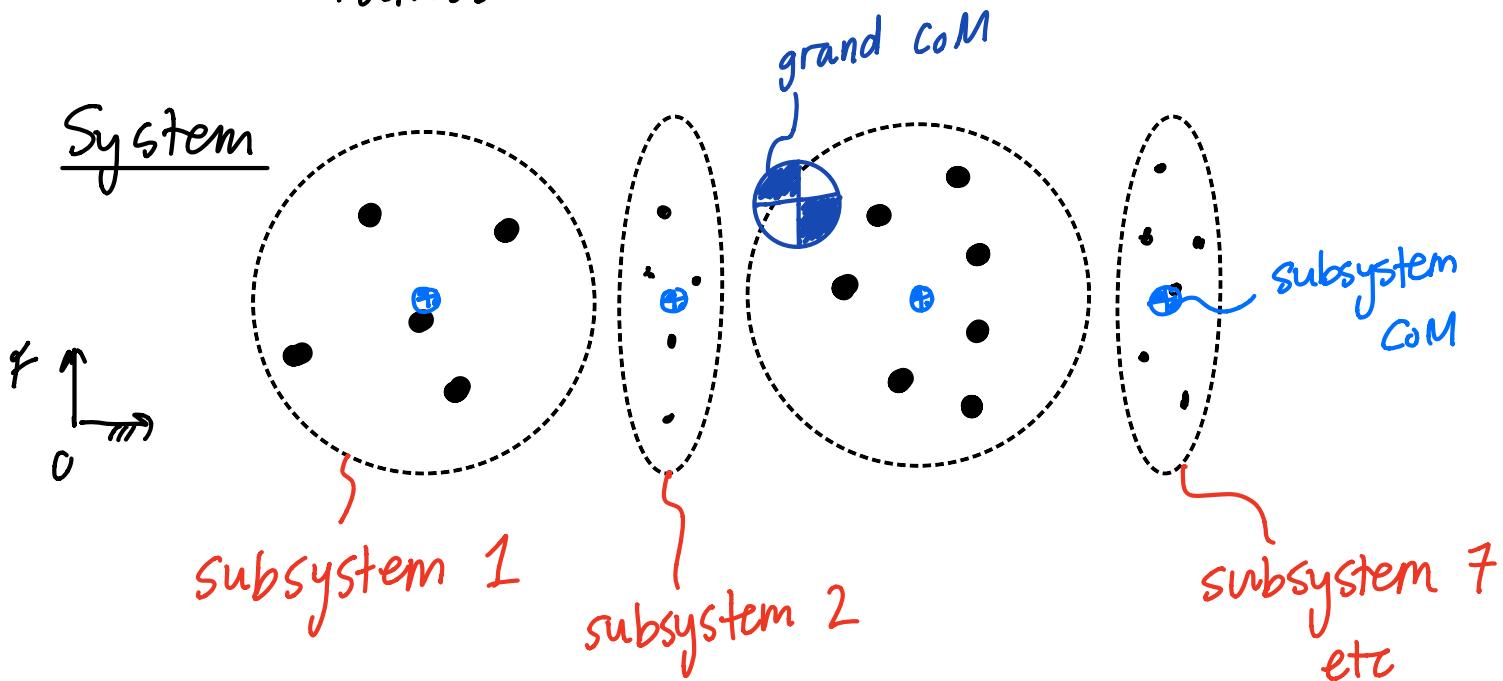


Today: Mechanics Review continued

$$\vec{L}, \vec{H}_{lc}, E_k, E_p$$

Frames



$$\begin{aligned} \square \quad \vec{L} &= \sum m_i \vec{v}_i \\ \circledcirc \quad &= \underbrace{\vec{L}_1 + \vec{L}_2 + \dots}_{\text{subsystems}} \\ \bullet \quad &= M_{\text{tot}} \vec{v}_G \end{aligned}$$

Linear momentum

$$\begin{aligned} \text{LMB: } * \sum_{\text{ext}} \vec{F} &= \dot{\vec{L}} \\ \circledcirc \quad &= M_{\text{tot}} a_G \\ \bullet \quad &= \dot{\vec{L}}_1 + \dot{\vec{L}}_2 + \dots \end{aligned}$$

* $\sum \vec{M}_{IC} = \sum_{\substack{\text{all particles} \\ \& \text{rigid bodies}}} \vec{r}_{i/C} \times m_i \vec{a}_{i/C} + \sum_{\substack{\text{rigid} \\ \text{bodies}}} \vec{w}_i I^{G_i}$

position of part or rigid object c.o.m }
the only eqn you need for all of mechanics (2D)

assumptions + theorem

$$= \overset{\bullet}{\vec{H}}_{IC}$$

fixed point moving at constant vel
c.o.m of system

$$\vec{H}_{IC} = \sum \vec{r}_{i/C} \times m_i \vec{v}_{i/C} + \sum I^{G_i} \vec{w}_i$$

□ $E_k = \sum \frac{1}{2} m_i |\vec{v}_i|^2 + \sum \frac{1}{2} I^{G_i} |\vec{w}_i|^2$

particles &
rigid objects

= $\frac{1}{2} m_{tot} |\vec{v}_G|^2 + \sum \frac{1}{2} m_i |\vec{v}_{i/G}|^2$

all mass
(includes rigid objects)

E_{KG}

$E_{K/G}$

Special case: single rigid object

$$E_k = \frac{1}{2} m_{tot} |\vec{v}_G|^2 + \frac{1}{2} I^G |\vec{w}|^2$$

• $\sum \vec{F}_i \cdot \vec{v}_i = \frac{d}{dt} (E_k)$

all forces (internal & ext)
Power

Special cases:

ex) single particle

$$\vec{F} \cdot \vec{v} = \frac{d}{dt} E_k$$

ex) arbitrary system

$$\left\{ \vec{F}_{\text{tot ext}} = m_{\text{tot}} \cdot a_G \right\}$$

$$\left\{ \sum_{\text{external}} F \right\} \cdot \vec{v}_G = \frac{d}{dt} E_{KG}$$

CoM Power $\underbrace{\frac{1}{2} m v_G^2}$

Some forces are conservative

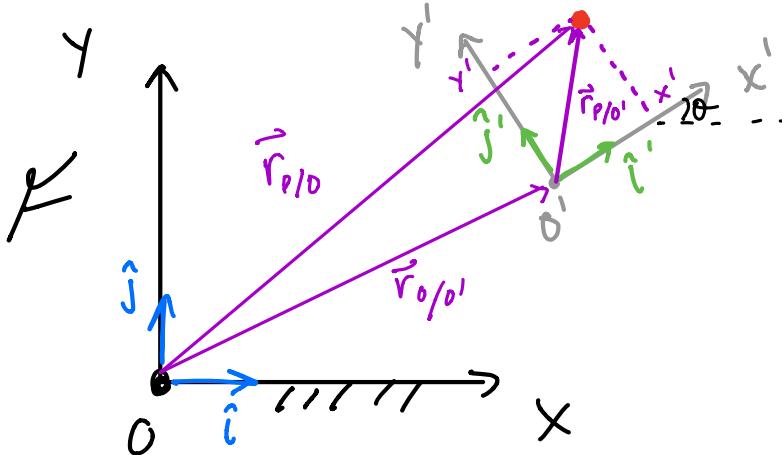
For conservative forces

$$P = - \underbrace{\dot{E}_p}_{\text{rate of decrease of potential energy}}$$

$$W = \int P dt = \int \vec{F} \cdot d\vec{r} = - \underbrace{\Delta E_p}_{\text{decrease in potential energy}}$$

decrease in potential energy

Reference Frames :



$$\begin{aligned}\dot{i}' &= \vec{\omega}_{B/q} \times i' \\ \dot{j}' &= \vec{\omega}_{B/q} \times j'\end{aligned}$$

$$\vec{v}_{P/B} = \dot{x}' \hat{i}' + \dot{y}' \hat{j}'$$

$$\vec{a}_{P/B} = \ddot{x}' \hat{i}' + \ddot{y}' \hat{j}'$$

$$\vec{r}_{P/O} = \vec{r}_{O'/O} + \vec{r}_{P/O'}$$

$$\vec{v}_{P/f} = \underbrace{\vec{v}_{O'/O}}_{\vec{v}_{O'/f}} + v_{P/B} + \vec{\omega}_{B/q} \times \vec{r}_{P/O'}$$

$$\vec{v}_{O'/f}$$

$$\vec{a}_{P/f} = \vec{a}_{O'/O} + \vec{a}_{P/B} + -\vec{\omega}_{B/q}^2 \vec{r}_{P/O'} + \vec{\omega}_{B/q} \times \vec{r}_{P/O'} + 2\vec{\omega}_{B/q} \times \vec{v}_{P/B}$$

"Q dot formula"

"transport theorem"

$$\underbrace{\frac{d\vec{Q}}{dt}}_{\dot{Q}_x \hat{i} + \dot{Q}_y \hat{j}} = \underbrace{\frac{d\vec{Q}}{dt}}_{\dot{Q}_{x'} \hat{i}' + \dot{Q}_{y'} \hat{j}'} + \vec{w} \times \vec{Q}$$